

Diff Eq:

$$(1) \quad \frac{d}{dt} \begin{pmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{pmatrix} = A \cdot \begin{pmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{pmatrix}.$$

A : constant coeff matrix.

sol'n: $\vec{x}(t) = e^{At} \cdot \vec{x}(0)$

where $e^{At} = I_n + At + \frac{1}{2!} (At)^2 + \frac{1}{3!} (At)^3 + \dots$

if $A = C^{-1} \cdot J \cdot C$, J Jordan form
 then $e^{At} = C^{-1} \cdot e^{Jt} \cdot C$

in special case, if A is diagonalizable.
 $J = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$
 $e^{Jt} = \begin{pmatrix} e^{\lambda_1 t} & & \\ & \ddots & \\ & & e^{\lambda_n t} \end{pmatrix}$

$\vec{x}(0)$ contain n free parameters, $x_1(0), \dots, x_n(0)$.

(2) Higher order const coeff equation: (Homog).

$$\left(\frac{d}{dt}\right)^n x(t) + a_1 \left(\frac{d}{dt}\right)^{n-1} x(t) + \dots + a_{n-1} \frac{d}{dt} x(t) + a_n x(t) = 0$$

we introduce new unknown functions:

$$x_0(t) = x(t)$$

$$x_1(t) = \frac{d}{dt} x(t)$$

$$\vdots$$

$$x_{n-1}(t) = \left(\frac{d}{dt}\right)^{n-1} x(t)$$

These new functions satisfy

$$\left(\frac{d}{dt}\right) \begin{pmatrix} x_0 \\ \vdots \\ x_{n-1} \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n-1} \\ \underbrace{-a_1 x_{n-1} \dots - a_n x_0}_{A} \end{pmatrix} = \begin{pmatrix} x_1(t) \\ \vdots \\ x_{n-1}(t) \\ -a_1 x_{n-1} \dots - a_n x_0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 & & & \\ \vdots & 0 & 1 & & \\ & \vdots & \vdots & \ddots & \\ 0 & & & & 1 \\ \underbrace{-a_n \quad -a_{n-1} \quad \dots \quad -a_1}_{A} & & & & \end{pmatrix} \begin{pmatrix} x_0 \\ \vdots \\ x_{n-1} \end{pmatrix}$$

this reduces to case (1).

the short way to solve this, is to find the characteristic polynomial:

try to ~~solve~~ ^{plug in} $x = e^{\lambda t}$.

get equation. $\underbrace{\left(\lambda^n + a_1 \lambda^{n-1} + \dots + a_n\right)}_{= \det(\lambda - A)} \cdot e^{\lambda t} = 0$

(3). Solving PDE of type. $\Delta_x u(t, x) = \dots$ $\partial_t u$, or $\partial_{tt} u, \dots$

Heat: $\partial_t u(t, x) = \partial_{xx} u(t, x)$.

we can use separation of variable to obtain.

"basis" of sol'n:

$$u(t, x) = f(t) \cdot g(x),$$

then

$$\partial_t (f(t) \cdot g(x)) = \partial_{xx} (f(t) \cdot g(x)).$$

$$\Leftrightarrow (\partial_t f) \cdot g = f \cdot \partial_{xx} g.$$

$$\Leftrightarrow \frac{\partial_t f(t)}{f(t)} = \frac{\partial_{xx} g(x)}{g(x)} = \text{const.}$$

if $f, g \neq 0$

$$\Rightarrow \begin{cases} \partial_t f(t) = \lambda f(t) & \Rightarrow f(t) = e^{\lambda t} f(0), \\ \partial_{xx} g(x) = \lambda \cdot g(x) & \Rightarrow g(x) = e^{\sqrt{\lambda} x} \cdot c_1 + e^{-\sqrt{\lambda} x} \cdot c_2. \end{cases} \text{ for some } \lambda.$$