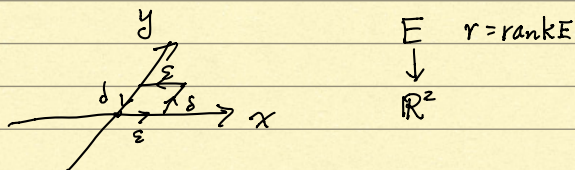


Recall last time:

- some formula for connections ∇ and curvatures F_∇ .
- Geometric meaning of curvature for vector bundle.



F_{12} component of F

$$F = F_{12} \cdot dx^1 \wedge dx^2, \quad F_{12}(x, y) \in M_r(\mathbb{R})$$

$$P_{(x, y)} = Id + \varepsilon \cdot \underbrace{F_{12}(x_0)}_{\text{as eqn in } M_r(\mathbb{R})} + \dots$$

$$\begin{aligned} \Rightarrow [\nabla^E, F_\nabla] &= \nabla^E \cdot F_\nabla - (-1)^2 \cdot F_\nabla \cdot \nabla^E \\ &= \nabla^E \cdot (\nabla^E \cdot \nabla^E) - (\nabla^E \cdot \nabla^E) \cdot (\nabla^E) \\ &= 0. \end{aligned}$$

$$\Rightarrow \nabla^{\text{End}(E)}(F_\nabla) = 0$$

(2) proof #2: work in local chart,

$$\begin{aligned} \nabla^E &= d + A \\ F &= \nabla^2 = d(A) + A \wedge A \\ &= d(A) + \frac{1}{2} [A, A] \end{aligned}$$

d: trivial connection on E w.r.t. the local trivialization.

Now, we need

$$= [\nabla^E, F] = [d + A, dA + \frac{1}{2} [A, A]]$$

$$= \underbrace{d(d(A))}_0 + \underbrace{d(\frac{1}{2} [A, A])}_0 + \underbrace{[A, dA]}_{\text{1-form}} + \underbrace{\frac{1}{2} [A, [A, A]]}_{\text{const matrix}}$$

$$A \in \Omega^1(U, \text{End}(E)). \quad A = \alpha_i \otimes \underline{T}_i$$

$$dA \in \Omega^2(U, \text{End}(E)) \quad dA = (d\alpha_i) \otimes \underline{T}_i$$

• Bianchi identity.

$$F \in \Omega^2(M, \text{End}(E)).$$

$$\text{End}(E) = \text{Hom}(E, E)$$



$\nabla^{\text{End}(E)}$ is a connection on $\text{End}(E)$.
i.e. for any $T \in \Omega^0(M, \text{End}(E))$.

$$\nabla^{\text{End}(E)}(T) = \nabla^E \cdot T - T \cdot \nabla^E$$

i.e. for $u \in \Omega^0(M, E)$,

$$(\nabla^{\text{End}(E)}(T))(u) = \nabla^E(Tu) - T(\nabla^E u)$$

in general: if $T \in \Omega^p(M, \text{End}(E))$

$$|T| = p, \quad |\nabla| = 1.$$

$$\nabla^{\text{End}(E)}(T) = [\nabla^E, T]$$

$$= \nabla^E \cdot T - (-1)^{|T| \cdot |\nabla|} \cdot T \cdot \nabla^E$$

• In case that $T = F_\nabla \in \Omega^2(M, \text{End}(E))$

$$\begin{aligned} \text{Indeed: } [A, [A, A]] &= \sum_{i,j,k} \alpha_i \wedge \alpha_j \wedge \alpha_k \cdot [T_i, [T_j, T_k]] \\ &= \frac{1}{3} \sum_{i,j,k} \alpha_i \wedge \alpha_j \wedge \alpha_k \{ [T_i, [T_j, T_k]] + [T_j, [T_k, T_i]] + [T_k, [T_i, T_j]] \} \\ &= 0 \end{aligned}$$

$A = \sum_i \alpha_i \otimes T_i$
 T_i matrix const
 α_i 1-form.

$$\Rightarrow \nabla(F) = 0. \quad (\text{Bianchi identity})$$

Today: connection on tangent bundle.

$$E = TM.$$

• Definition: torsion tensor. T .

given a connection ∇ on TM ,

$$T: \text{Vect}(M) \times \text{Vect}(M) \rightarrow \text{Vect}(M)$$

$X, Y \in \text{Vect}(M)$

$$T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y].$$

(2) $\forall f \in C^\infty(M)$

$$T(fX, Y) = f T(X, Y).$$

$$\begin{aligned} \text{indeed: } T(fX, Y) &= \nabla_{fX} Y - \nabla_Y (fX) - [fX, Y] \\ &= f \cdot \nabla_X Y - f \cdot \nabla_Y X - Y(f) \cdot X - f[X, Y] \end{aligned}$$

$\therefore T \in \Omega^2(M, TM)$. torsion.

• In local chart, given local coords $x^1, \dots, x^n$ on U , $\exists \{\partial_{x^1}, \dots, \partial_{x^n}\}$ on $TM|_U$.

$$\nabla_{\partial_i}(\partial_j) = \Gamma_{ij}^k \partial_k$$

recall $\nabla_{\partial_i}(e_\alpha) = \Gamma_{i\alpha}^\beta e_\beta$

Γ_{ij}^k is the Christoffel symbol (??).

$T(\partial_i, \partial_j) = T_{ij}^k \partial_k$ (sum over k)

$$\begin{aligned} T(\partial_i, \partial_j) &= \nabla_{\partial_i}(\partial_j) - \nabla_{\partial_j}(\partial_i) - \underbrace{[\partial_i, \partial_j]}_0 \\ &= \Gamma_{ij}^k \partial_k - \Gamma_{ji}^k \partial_k \\ &= (\Gamma_{ij}^k - \Gamma_{ji}^k) \partial_k \end{aligned}$$

so torsion tensor measure the a -symmetry of Γ_{ij}^k in i, j indices.

If $T=0$, we say ∇ is torsionless or symmetric.

Levi-Civita connection:

• Given a g Riemannian metric. There exist a unique connection ∇ , s.t.

$$T_\nabla = 0, \quad \nabla(g) = 0.$$

g , the metric tensor.

$$g(X, Y) \in C^\infty(M).$$

$$g \in \Gamma(M, T^*M \otimes T^*M).$$

∇ is a connection on TM .

$\rightarrow$ $\begin{matrix} - & - & - & \text{on } T^*M \\ - & - & - & \text{on } T^*M \otimes T^*M \end{matrix}$

$$\nabla(g) = 0$$

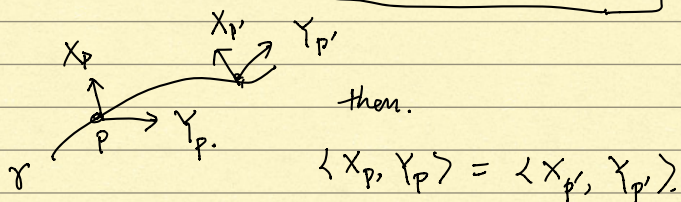
$$\Leftrightarrow \forall X, Y, Z \in \text{Vect}(M).$$

$$\nabla_Z(g(X, Y))$$

always true.

$$(\nabla_Z g)(X, Y) + g(\nabla_Z X, Y) + g(X, \nabla_Z Y).$$

$$\boxed{\nabla_Z(g(X, Y)) = g(\nabla_Z X, Y) + g(X, \nabla_Z Y)}$$



i.e. parallel transport preserves inner product.

(4.1.3) [Ni].

$$\begin{aligned} g(\nabla_X Z, Y) &= \frac{1}{2} \{ X g(Y, Z) - Y(g(Z, X)) \\ &\quad + Z g(X, Y) - g([X, Y], Z) \\ &\quad + g([Y, Z], X) - g([Z, X], Y) \}. \end{aligned}$$

more useful formula in Christoffel symbol:

$$\Gamma_{jk}^i = \frac{1}{2} g^{il} (-\partial_i g_{jk} + \partial_j g_{kl} + \partial_k g_{jl})$$

notice it is symmetric in $j \leftrightarrow k$.

$$\Gamma_{ijk} := g(\nabla_{\partial_j} \partial_k, \partial_i) \quad \Gamma_{jk}^i = g^{il} \cdot \Gamma_{ljk}.$$

$$\nabla_{\partial_j}(\partial_k) = \nabla_{\partial_k}(\partial_j) \quad (\because T=0).$$

